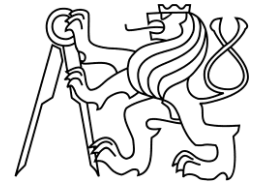# Data Fusion for a Mobile Exploratory Robot

Fusion of distinct sensor **data** regarding their strong and weak points to provide reliable and precise **localization** of a mobile *Search&Rescue* robot *NIFTi* in **challenging** environments

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